

DESCRIPTION

The CAN I/O & CAN PLC Waterproof module is a compact controller automotive for applications. Its high IP 68 protection rating (permanently waterproof and dustproof) combination with programmable graphical software make it the ideal solution for a wide range of automotive applications.

mounting direction

view of plug

TECHNICAL DATA

Housing

Delphi / Aptiv - 211PC249S0033 Connector Housing dimensions 60 x 60 x 30 mm (housing only) 95 x 77.3 x 33.5 mm (incl. tabs and connector) Weight 170 g Temperature range -40 to +85 °C (at +85 °C rated (ISO 16750-4 compliant) power see page 5) **Environmental Protection IP68** 30 mA Current consumption Over-current Protection 20 A Total Inputs and outputs 14 (6 inputs, 8 I/O's) Inputs Configurable as: Digital, positive encoder signal analog (0...11.4 / 33.68 V) Depending on assembly: Digital, low side switch encoder signal frequency input analog input (0...24.5 mA, PT1000 sensor) Configurable as: Outputs Digital, positive switching (high side) Depending on assembly: PWM output (3 Hz...500 Hz) reference voltage source (5 V/8 V) Operating voltage 12 V (Code C) and 24 V (Code E) ISO 16750-2 compliant Starting voltage 8 V Overvoltage protection ≥ 33 V Undervoltage cut-off 8 V Quiescent current 97 μA (at 24 V); 8.5 μA (at 12 V); at

Yes

Moulded plastic, sealed

REGULATORY APPROVALS AND TESTING

CE conformity	compliant
E1 label	UN/ECE-R10 radiated immunity with 100 V/m conducted immunity with 100 mA(BCI)
E1 approval	06 7181
Electrical tests	According to ISO 16750 – 2/ 16750-4: Short circuit protection (Exception: RS232 interface) Pin/connector Interruption Overvoltage at +65 °C Operation/storage test at +85 °C Superimposed alternating voltage Slow decrease and increase of supply voltage Momentary drop in supply voltage Reset behavior at voltage drop According to ISO 7637 - 2: Pulse 1, 2a, 2b, 3a, 3b Load dump test CNH-82036374-K-MP-180-E; (par. 13.7.10.3) 12V, R, 4Ω, U _s .58V

SOFTWARE/PROGRAMMING

Programming System

MRS Developers Studio

MRS Developers Studio with built-in functions library, similar to programming with FUP. Custom software blocks can be integrated into "C-code". Program memory is sufficient for about 300 basic logic components.

Reverse polarity

protection

CAN interfaces

Baudrate

assembly variants with reference output higher ca. 4,7 mA

CAN bus interface 2.0 A/B, ISO

11898-2 compliant

60 kbps ...1000 kbps default: 125 kbps

DATASHEET CAN I/O AND PLC WP 1.053.

Input frequency

Turn-on threshold

Turn-off threshold

Input resistance

Input frequency
Turn-on threshold
Turn-off threshold



INPUT FEATURES - SUMMARY

Pin C3, C4, C5, C6, C7	Usable as analog or digital input Resolution Accuracy	12 Bit ± 1 % full scale	Pin A1, A2, A3, A4, A5, A6	Usable as analog or digital input Resolution Accuracy	12 Bit ± 1 % full scale	
Voltage input 011.4 V (see <u>A</u>)	Input resistance Input frequency Accuracy	22,7 kΩ f_g^{1} = 60 Hz ± 3 % max.	Voltage input 011.4 V (see <u>E</u>)	Input resistance Input frequency Accuracy	16 k Ω f _g ¹ = 60 Hz ± 5 %	
Current input 024,5 mA (see $\underline{\mathbb{C}}$)	Input resistance Input frequency Conversation factor	500 Ω 40 Hz 1mA ≈ 462 Digits	Digital input positive (see $\underline{\underline{E}}$)	Input resistance Input frequency Turn-on threshold Turn-off threshold	16 kΩ f _g ¹ = 60 Hz 6,5 V 5 V	
Frequency input (see D)	Input resistance Input frequency	22,7 kΩ ± 3% accuracy at				
, <i>–</i> ,	Turn-on threshold Turn-off threshold	≤ 2.2 kHz 6,5 V 5 V	Pin A7, A8	Usable as analog or digital input Resolution Accuracy	12 Bit ± 1 % full scale	
Digital input positive (see A)	Input resistance Input frequency Turn-on threshold Turn-off threshold	22,7 kΩ f ₂ = 60 Hz 7 V 4,5 V	Digital input positive (see <u>E</u>)	Input resistance Input frequency Turn-on threshold Turn-off threshold	22,7 kΩ f _g '= 60 Hz 6,5 V 5 V	
Pin C2	Usable as analog or digital input Resolution Accuracy	12 Bit ± 1 % full scale				
Voltage input 033,68 V (see B)	Input resistance Input frequency Accuracy	66,6 kΩ f_g^{1} = 40 Hz ± 3 %				
Current input 024,5 mA (see $\underline{\mathbb{C}}$)	Input resistance Input frequency Conversion factor	470 Ω 40 Hz 1mA ≈ 462 Digits				
Frequency input	Input resistance	22,7 kΩ				

± 3% accuracy at ≤ 2.2 kHz

7 V

4,5 V

66,6 kΩ f_g¹= 40 Hz 19 V

14,3 V

(see □)

Digital input

positive (see B)

¹ cutoff frequency (-3 dB)

DATASHEET CAN I/O AND PLC WP 1.053.



OUTPUT FEATURES - SUMMARY

Pin A1, A2	1, A2 Protective circuit for Optionally Pin A3, A4, A5, inductive loads integrated A6, A7, A8		Protective circuit for inductive loads	Optionally integrated	
	Wire fault diagnostics	Possible via current sense		Wire fault diagnostics	Possible via current sense
	Short circuit diagnostics	Possible via current sense		Short circuit diagnostics	Possible via current sense
Digital, positive switching (high side; see \underline{E})	Switching voltage Switching current Conversion factor current sense	hing current 0,02-2,5 A ersion factor		Switching voltage Switching current Conversion factor current sense	9-32 V DC 0,02-2,5 A 1 Digit ≈ 2,3 mA
Short circuit re-sistance against GND and V _B	Switching-off is controlled by high side driver (separate for each channel)		PWM-output (see E)	Output frequency Duty cycle Resolution Switching current	500 Hz 01000 ‰ 1 ‰ ≥ 2,5A (see page 5)
			Short circuit resistance against GND and V _B	Switching-off is controll driver (separate for each	, ,

PERFORMANCE TESTS HIGH SIDE DRIVER VNQ5050AK

Test without PWM				Test with PWM			
	Test No.	Load	Endurance		Test No.	Load	Endurance
Endurance tests at +85 °C for digital	1	4 x 2,5 A	Continous	Endurance tests at +85 °C for PWM outputs with frequency=200 Hz and 90 % duty cycle	1	4 x 2,0 A	Continous
outputs (max. 2 channels	2	3 x 2,5 A 1 x 3,5 A	30 minutes		2	4 x 2,5 A	10 minutes
per high side driver)	3	2 x 2,5 A 2 x 3,5 A	15 minutes		3	1 x 3,5 A 3 x 2,5 A	2 minutes
	4	1 x 2,5 A 3 x 3,5 A	10 minutes	(max. 2 channels per high side driver)	4	2 x 3,5 A	2 minutes
	5	2 x 5 A	5 minutes				



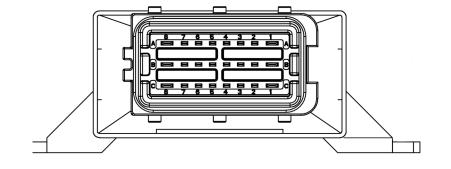
PIN ASSIGNMENT POWER SUPPLY AND INTERFACES

Pin	Description
B1	Supply voltage for output pins A1 through A4, operating voltage for CPU
B2	CAN bus 1 high
В3	CAN bus 1 low
B4	CAN bus 1 high/RS 485 – A/RS 232 Tx (optional, see page 7)
B5	CAN bus 1 low/RS 485 – B/RS 232 Rx (optional, see page 7)

Pin	Description
В6	Ground/contact 31 according to DIN 72552 CAN bus high
В7	VREF (assembly option see page 7, otherwise not connected)
В8	Supply voltage for output pins A5 through A8, operating voltage for CPU
C1	Ground/contact 31 according to DIN 72552 CAN bus high
C8	Battery/ignition contact 15 according to DIN 72552, optional as DI (see page 7) Supply pull-up inputs

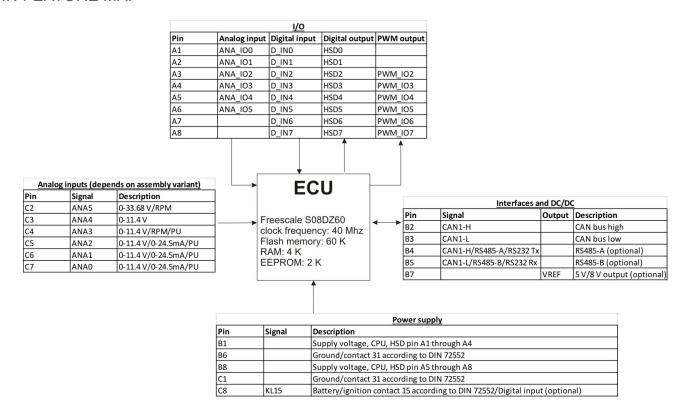
PIN ASSIGNMENT INPUTS AND OUTPUTS

Pin	Signal	Description	Pin	Signal	Description	
A1	ANA_IO0 / D_IN0 OUT_HSD0	Analog/digital input IO0 0-11.4 V or digital output DO0	A8	D_IN7 OUT_HSD7	Digital input IO7; 0-11.4 V or digital output DO7 with PWM	
A2	ANA_IO1 / D_IN1 OUT_HSD1	Analog/digital input IO1; 0-11.4 V or digital output DO1	C2	ANA5/ D_ANA5	capability Analog input 5; 0-33.68 V	
А3	ANA_IO2 / D_IN2	Analog/digital input IO2; 0-11.4 V			can also be used as digital inpu	
	OUT_HSD2	or digital output DO2 with PWM capability	C3	ANA4/ D_ANA4	Analog input 4; 0-11.4 V can also be used as digital input	
A4	ANA_IO3 / D_IN3 OUT_HSD3	Analog/digital input IO3; 0-11.4 V or digital output DO3 with PWM capability	C4	ANA3/ D_ANA3	Analog input 3; 0-11.4 V can also be used as digital input	
A5	ANA_IO4 / D_IN4 OUT_HSD4	Analog/digital input IO4; 0-11.4 V or digital output DO4 with PWM	C5	ANA2/ D_ANA2	Analog input 2; 0-11.4 V can also be used as digital input	
		capability	C6	ANA1/ D_ANA1	Analog input 1; 0-11.4 V	
A6	ANA_IO5 / D_IN5	Analog/digital input IO5; 0-11.4 V			can also be used as digital input	
	OUT_HSD5	or digital output DO5 with PWM capability	C7	ANA0/ D_ANA0	Analog input 0; 0-11.4 V can also be used as digital input	
A7	D_IN6 OUT_HSD6	Digital input IO6; 0-11.4 V or digital output DO6 with PWM capability				

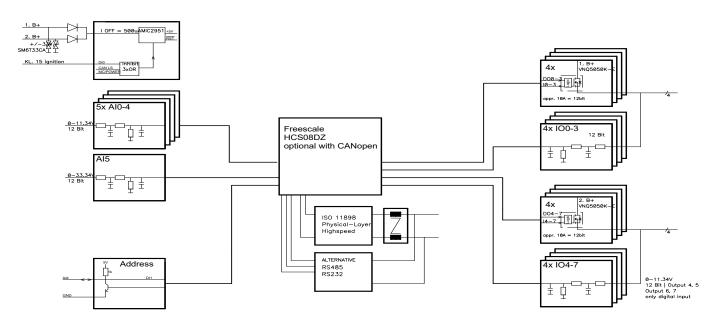




PIN FEATURE MAP



BLOCK FUNCTION DIAGRAM

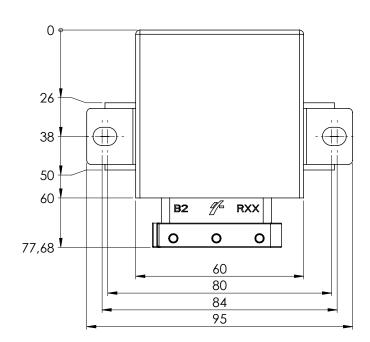


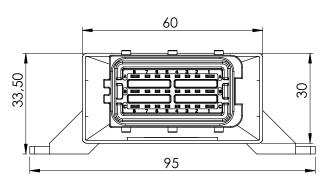
BLOCK FUNCTION DIAGRAM FOR ASSEMBLY OPTIONS





TECHNICAL DRAWING (IN MM)





DATASHEET CAN I/O AND PLC WP 1.053.



ASSEMBLY OPTIONS AND ORDER INFORMATION

			Inp	uts				Outputs	CAN Bus High Speed	Serial Interface	DC/DC	Proces- sor
	A Voltage 0 – 11.4 V	B Voltage 0 – 33 V	C Current 0 - 24 mA	D Fre- quency Hz	Sensor inputs 10 kΩ Pull-up	E I/O´s (can be u analog or digital as digital ou	inputs or	F PWM ≤ 500 Hz			5 Volt Referenz 8 Volt Referenz	
1.053.300.0000	C3,C4,C5,C6,C7	C2				A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8				DZ60
1.053.302.0000	C3,C5,C6,C7			C2,C4		A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8			B7 (5 V)	DZ60
1.053.302.1200	C3,C5,C6,C7			C2,C4		A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8			B7 (5 V)	DZ60
1.053.302.1300	C3,C5,C6,C7			C2,C4		A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8			B7 (5 V)	DZ128
1.053.303.0000	C3,C4	C2	C5,C6,C7			A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8				DZ60
1.053.304.1200	C3,C5,C6,C7			C2,C4	C2,C4	A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8			B7 (5 V)	DZ60
1.053.305.0000	C3,C5,C6,C7			C2,C4		A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8			B7 (8 V)	DZ60
1.053.306.0000	C3,C4	C2			C5,C6,C7	A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8				DZ60
1.053.307.0000	C3	C2			C4,C5,C6,C7	A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8				DZ60
1.053.307.0001	C3	C2			C4,C5,C6,C7	A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8				DZ128
1.053.310.0000	C3,C4,C5,C6,C7	C2				A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8		B4/B5 (RS485)		DZ60
1.053.320.1000	C3,C4,C5,C6,C7	C2				A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8		B4/B5 (RS232)		DZ128
1.053P.300.0000	C3,C4,C5,C6,C7	C2				A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8	CANopen			DZ60
1.053P.305.0000	C3,C5,C6,C7			C2,C4		A1,A2,A3,A4,A5	,A6,A7,A8	A3,A4,A5,A6,A7,A8	CANopen		B7 (8 V)	DZ60

Order number with the last 4 digits 1000 or 1200 indicate that the device is active after the supply voltage is connected to pins B1 and B8 (operating voltage contact 30); pin C8 (ignition contact 15) can be used as digital input in this case.

Page 7 of 11 ©MRS Electronic GmbH & Co. KG Subject to change without notice! Version 2.1

DATASHEET CAN I/O AND PLC WP 1.053.



ACCESSORIES

Description	Order number
Programming tool MRS Developers Studio	1.100.100.09
Cable set CAN I/O WP	112342
Connector package CAN I/O WP	110421
Protection cap	111441
Crimp contact 2,8 mm/1-2,5 mm ²	109947
Crimp contact 1,5 mm/1,3-2 mm ²	109949
Dummy FCI filler plug	110268
PCAN-USB Interface	105358



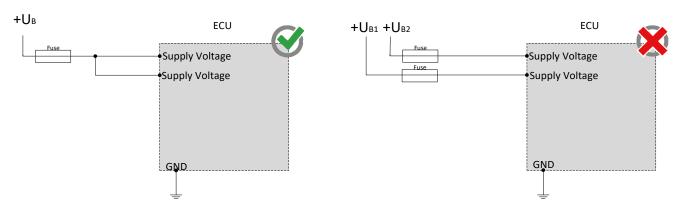
MANUFACTURER

MRS Electronic GmbH & Co. KG Klaus-Gutsch-Str. 7 78628 Rottweil

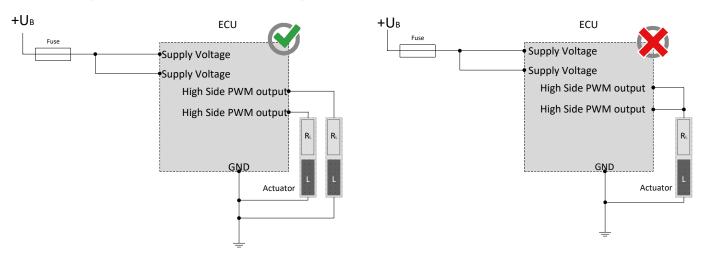


NOTES ON WIRING AND CABLE ROUTING

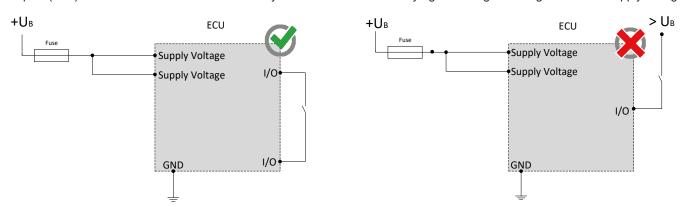
The electronic system and the power outputs of a control unit must be supplied by the same power supply system.



PWM outputs may not be connected with each other or bypassed.



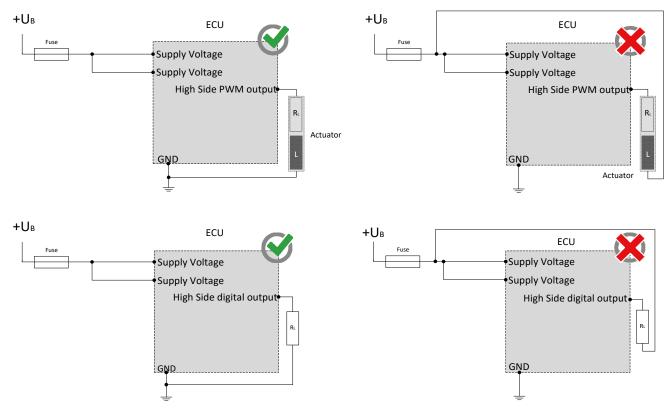
The pins (I/Os) can be used in combination and may not be switched externally against a higher voltage level than supply voltage.



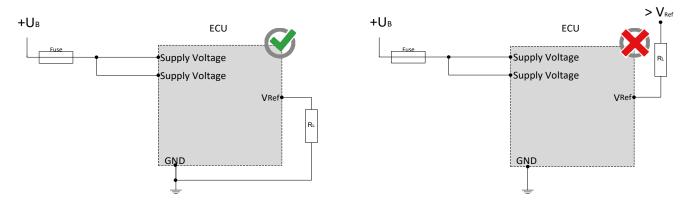


NOTES ON WIRING AND CABLE ROUTING

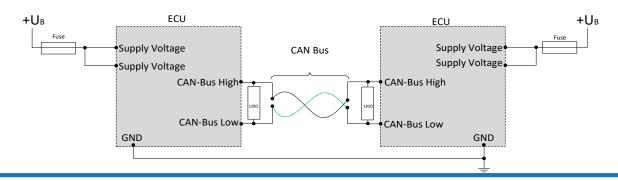
Higside outputs may only be switched to ground.



The sensor supplies can be "lifted" through an external circuitry, for example the creation of higher voltage, as they only work as a voltage source but not as voltage drain. The lift of a voltage source may lead to unforeseen malfunctions and damages of the control unit in case of permanent operation.



CAN bus communication is the main communication between the control unit and the vehicle. Therefore, connect the CAN bus with special care and check the correct communication with the vehicle to avoid undesired behavior.



DATASHEET CAN I/O AND PLC WP 1.053.



SAFETY AND INSTALLATION INFORMATION

It is essential to read the instructions in full thoroughly before working with the device.

Please note and comply with the instructions in the operating instructions and the information in the device data sheet, see www.mrs-electronic.de **Staff qualification:** Only staff with the appropriate qualifications may work on this device or in its proximity.

SAFFTY



WARNING! Danger as a result of a malfunction of the entire system.

Unforeseen reactions or malfunctions of the entire system may jeopardise the safety of people or the machine.

· Ensure that the device is equipped with the correct software and that the wiring and settings on the hardware are appropriate.



WARNING! Danger as a result of unprotected moving components.

Unforeseen dangers may occur from the entire system when putting the device into operation and maintaining it.

- · Switch the entire system off before carrying out any work and prevent it from unintentionally switching back on.
- · Before putting the device into operation, ensure that the entire system and parts of the system are safe.
- The device should never be connected or separated under load or voltage.



CAUTION! Risk of burns from the housing.

The temperature of the device housing may be elevated.

• Do not touch the housing and let all system components cool before working on the system.

PROPER USE

The device is used to control or switch one or more electrical systems or sub-systems in motor vehicles and machines and may only be used for this purpose. The device may only be used in an industrial setting.



WARNING!Danger caused by incorrect use.

The device is only intended for use in motor vehicles and machines.

- Use in safety-related system parts for personal protection is not permitted.
- Do not use the device in areas where there is a risk of explosion.

Correct use:

- · operating the device within the operating areas specified and approved in the associated data sheet.
- · strict compliance with these instructions and no other actions which may jeopardise the safety of individuals or the functionality of the device.

Obligations of the manufacturer of entire systems

It is necessary to ensure that only functional devices are used. If devices fail or malfunction, they must be replaced immediately.

System developments, installation and the putting into operation of electrical systems may only be carried out by trained and experienced staff who are sufficiently familiar with the handling of the components used and the entire system.

It is necessary to ensure that the wiring and programming of the device does not lead to safety-related malfunctions of the entire system in the event of a failure or a malfunction. System behaviour of this type can lead to a danger to life or high levels of material damage.

The manufacturer of the entire system is responsible for the correct connection of the entire periphery (e.g. cable cross sections, correct selection/connection of sensors/actuators).

Opening the device, making changes to the device and carrying out repairs are all prohibited. Changes or repairs made to the cabling can lead to dangerous malfunctions. Repairs may only be carried out by MRS.

Installation

The installation location must be selected so the device is exposed to as low a mechanical and thermal load as possible. The device may not be exposed to any chemical loads.

Install the device in such a manner that the plugs point downwards. This means condensation can flow off the device. Single seals on the cables/leads must be used to ensure that no water gets into the device.

Putting into operation

The device may only be put into operation by qualified staff. This may only occur when the status of the entire system corresponds to the applicable guidelines and regulations.

FAULT CORRECTION AND MAINTENANCE



NOTE The device is maintenance-free and may not be opened.

• If the device has damage to the housing, latches, seals or flat plugs, it must be taken out of operation.

Fault correction and cleaning work may only be carried out with the power turned off. Remove the device to correct faults and to clean it.

Check the integrity of the housing and all flat plugs, connections and pins for mechanical damage, damage caused by overheating, insulation damage and corrosion. In the event of faulty switching, check the software, switches and settings.

Do not clean the device with high pressure cleaners or steam jets. Do not use aggressive solvents or abrasive substances.